



## **Model 3125-01A**

**PCB L&T Rotary Torque Transducer (Slip Ring), 5,000 in-lb/417 ft-lb (565 N-m) rated capacity,  
100% static overload protection, 1 1/2-in (38.1 mm) Shaft**

### **Installation and Operating Manual**

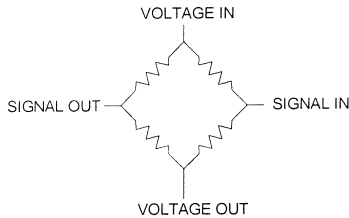
**For assistance with the operation of this product,  
contact the PCB Piezotronics, Inc.**

**Toll-free: 716-684-0001  
24-hour SensorLine: 716-684-0001  
Fax: 716-684-0987  
E-mail: [info@pcb.com](mailto:info@pcb.com)  
Web: [www.pcb.com](http://www.pcb.com)**



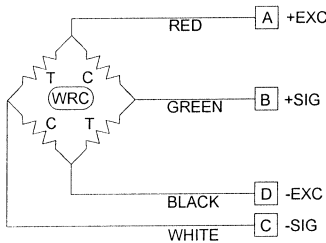
## 1.0 INTRODUCTION

Load Cells manufactured by the Force/Torque Division of PCB Piezotronics are designed to accurately measure static and quasi-static compressive and tensile forces ranging from 5 lbs. to 100k lbs. (22 to 4.45kN). All models utilize strain gages configured into a Wheatstone Bridge Circuit to produce the primary sensing element. The four-arm Wheatstone Bridge configuration is shown below in **Figure 1**.



**Figure 1 - Wheatstone Bridge Circuit**

Most PCB load cells follow a wiring code established by the Western Regional Strain Gage Committee as revised in May 1960. The wiring code is as follows:



**Figure 2 - Western Regional Strain Gage Committee Wiring Code**

Refer to the wiring drawing included with this manual for specific wiring of the supplied load cell.

The gages are bonded to the load cell's structure. Typically, a regulated DC or AC excitation is applied between A and D of the bridge. When a force is applied to the load cell, the Wheatstone Bridge becomes unbalanced, causing an output voltage between B and C, which is proportional to the applied load. The magnitude of the output voltage corresponds to the deformation of the load cell and therefore the applied load. This configuration allows for temperature and pressure compensation, as well as cancellation of signals caused by forces not directly applied to the axis of the applied load. Output is typically expressed in units of millivolt per volt of excitation.

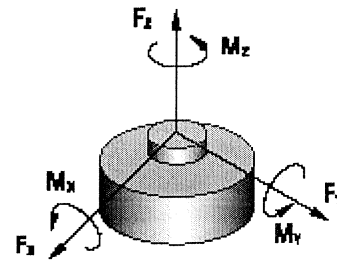
Optional signal conditioners are available from PCB. A signal conditioner may have analog voltage output, current output, or

digital output. Digital display signal conditioners are also available.

### Axis Definition

PCB force products comply with the Axis and Sense Definitions of NAS-938 (National Aerospace Standard-Machine Axis and Motion) nomenclature and recommendations of the Western Regional Strain Gage committee. These axes are defined in terms of a "Right Handed" orthogonal coordinate system as show below.

A (+) sign indicates force in a direction that produces a (+) signal voltage and generally defines a tensile force. The primary axis of rotation or axis of radial symmetry of a load cell is the z-axis as defined in **Figure 3**.



**Figure 3 - Axis and Sense Nomenclature for PCB Load Cells**

## 2.0 SAFETY INFORMATION

Failure of the load cell structure or fasteners used in the load cell installation may cause personal injury and equipment damage. To prevent structure failure, review the extraneous load limits listed on the load cell specification sheet supplied with this manual.

Loads must be limited to 100% of the measurement axis load combined with 200% of any one of the extraneous loads. To determine an acceptable level of extraneous loads that prevents output signal degradation, review the extraneous load limits and note on the specification sheet.

When selecting rod ends and fasteners for load cell installation, review the manufacturers data to determine if failure might occur due to combined measurement axis and extraneous loads.

## 3.0 MECHANICAL INSTALLATION

Refer to the outline drawing supplied with this manual for specific outline dimensions and installation details for your particular model. The specification is also included to provide details of the sensor's characteristic properties.

**General Purpose Load Cells**

It is important that the surface to which each load cell is mounted be clean and perfectly flat to avoid flexing of the base, which could affect sensor sensitivity and result in erroneous data. Ideally, surface flatness should be held to within 0.001" (TIR) over the entire mating surface. Ensure that the sensor is correctly aligned and oriented, and that it is mounted with proper torque and hardware.

If the load cell is used in an application where both tension and compression forces are applied, use spherical rod end bearings to eliminate bending loads. A load button should be used in compression-only applications.

Extraneous loads, such as bending moments and side loads, may reduce measurement accuracy and cause structure damage. Install the load cell in a manner that minimizes these loads.

**Fatigue Rated Load Cells**

Fatigue rated load cells are specially designed and manufactured to withstand millions of cycles. They are manufactured using premium fatigue resistant steel and special processing to insure mechanical and electrical integrity as well as accuracy. Fatigue rated load cells manufactured by the Force/Torque Division are guaranteed to last 100 million fully reversed cycles (full tension through zero to full compression). An added benefit of fatigue rated load cells is that they are extremely resistant to extraneous bending and side loading forces.

**Mounting Bases**

All low-profile load cells are calibrated with a mounting base. An optional mounting base, if purchased with a load cell, is pre-installed at the factory. Unless otherwise specified, the base and load cell are calibrated as a unit. It is important to note that the performance of the load cell may be affected if the factory-installed mounting base is removed or modified.

Steel hex head cap screws used in mounting load cells must be rated Grade 8 or better. Screws should be fastened in a criss-cross pattern, and tightened to the appropriate torque value listed below.

Screw Thread	Torque (foot-pounds)
1/4"-28	15
3/8"-24	50
1/2"-20	130
5/8"-18	260

Figure 4 – Screw Torque Values

**Rod-Style Load Cell**

Loads applied to rod-style load cells must be even and centered. Compensation linkages (e.g. rod end bearings, alignment couplers) are recommended to help minimize load

misalignment. When installing fixtures, thread the fixture to the load cell, not the load cell to the fixture. If alignment fixtures are not used, insure loading surfaces are flat and parallel, with loads applied in line with the sensor.

**S-Beam Load Cell**

S-beam load cells can be mounted in a variety a ways, depending on the end use of the sensor. In tension applications, loads must be applied in line, centered on the sensor. To insure optimum loading, compensation linkages such as rod end bearings and alignment couplers are recommended.

In compression applications, loads must be applied even and centered. Load surfaces must be clean, flat and parallel. A load button mounted to the top of the sensor, with the sensor bottom secured to a base plate, provides a reliable mounting arrangement.

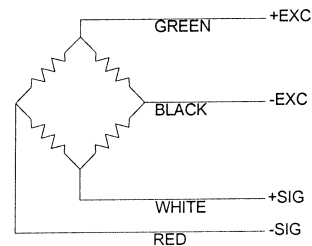


Figure 5 - S-Beam Load Cell Wiring Diagram

If fixtures are mounted to the load cell, be sure to thread the fixture to the load cell. Threading the load cell to the fixture may inadvertently apply a torque load that could damage the sensor.

**Hollow Compression Load Cells**

Hollow compression load cells feature a smooth thru-hole design that allows a load structure to pass directly through the load cell itself. The load structure must contact the top inner ring only, and the support fixture must contact the lower outer ring only. Hardened washers are supplied and should be used between the load cell and mounting surfaces to obtain the best performance.

**Load Washer**

Load washer load cells were originally designed to determine the clamp force vs. torque on fasteners. As torque is applied to a fastener, a tensile loading occurs on the fastener, which results in compression load on the load cell. Hardened washers are supplied and should be used between the load cell and mounting surfaces to obtain the best performance.

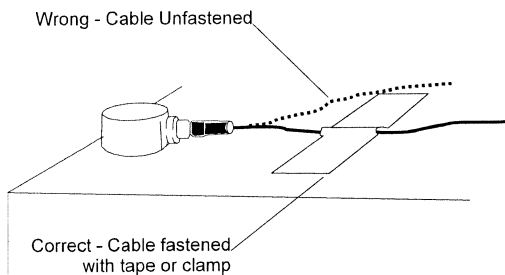
### Load Button

Load buttons are compact, compression-only load cells with an integral spherical loading surface. It is extremely important that the mounting surface is clean, flat and even. Loads must be applied in line on the center of the button to insure optimum sensor performance. Loads must not contact the sensor diaphragm. Fixtures used with load buttons must be oriented in line with the sensor.

## 4.0 ELECTRICAL INSTALLATION

For proper electrical connections, refer to the installation drawing for the load cell, and the wiring drawing for the signal conditioner used. Construct the interconnect cable from high-quality shielded instrumentation cable. Various cable assemblies are available through PCB.

Connect one end of the cable to the sensor connector and the other end to the signal conditioner. Make sure to tighten the cable connector to the sensor. For installation in dirty, humid, or rugged environments, it is suggested that the connection be shielded against dust or moisture with shrink tubing or other protective material. Strain relieving the cable/sensor connection can also prolong cable life. Mounting cables to a test structure with tape, clamps, or adhesives minimizes cable whip. (See **Figure 6** for an example of a sensor installation with a securely fastened cable.)



**Figure 6 - Cable Strain Relief**

## 5.0 POLARITY

Compressive forces upon standard PCB tension/compression load cells produce a negative-going voltage output. Tensile forces produce a positive-going voltage output.

Compressive forces upon a compression-only load cell produce a positive-going signal.

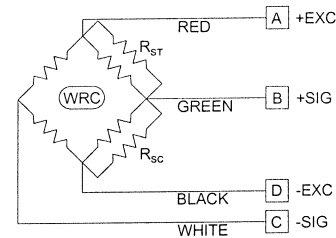
## 6.0 SHUNT CALIBRATION

Shunt calibration is the known, electrical, unbalancing of a strain gage bridge by means of a fixed resistor that is placed, or “shunted”, across one leg of the bridge. The “Wheatstone Bridge” utilized by PCB load cells are typically calibrated using the shunt calibration technique.

Shunt calibration is a method of periodically checking the gain or span of a signal conditioner, which is used in conjunction with a strain gage based transducer, without exposing the transducer to known, traceable, physical input values. If required, adjustments can then be made to the signal conditioner to insure accurate measurement results.

The strain gage bridge is “in balance” when the host mechanical structure is unloaded and unstressed. As the host structure (diaphragm, bending beam, shear beam, column, etc.) is loaded or stressed, the Wheatstone Bridge becomes unbalanced, resulting in an output signal that is proportional to the applied load.

Shunt calibration simulates the mechanical input to a transducer by unbalancing the bridge with a fixed resistor placed across, or in parallel with, one leg of the bridge. For tension shunt calibration, or +CAL, the shunt resistor ( $R_{st}$ ) is shunted across the +Excitation (A) and +Signal (B) leg of the bridge. For compression shunt calibration, or -CAL, the shunt resistor ( $R_{sc}$ ) is shunted across the -Excitation (D) and +Signal (B) leg of the bridge. Refer to **Figure 7** for shunt resistor locations in the Wheatstone Bridge circuit.



**Figure 7 - Shunt Resistor Locations**

Shunt calibration is accepted throughout the industry as a means of periodic calibration of a signal conditioner and transducer between calibrations of known, applied, traceable, mechanical, input values. Consequently, most all strain gage transducer manufacturers collect and supply shunt calibration data, along with a shunt calibration resistor, as a standard feature.

### Shunt Calibration Procedure

1. Connect the transducer to an appropriate strain gage signal conditioner and allow adequate time for the system to stabilize.
2. Apply a full-scale, N.I.S.T. traceable, mechanical input (or load) to the transducer.
3. Adjust the signal conditioner's gain or span controls, as required, to obtain a full-scale electrical output signal, and/or numeric display that represents the applied, mechanical input quantity.
4. Remove the mechanical input (or load).

**Shunt Calibration Procedure – continued**

5. Place the shunt calibration resistor across an appropriate leg of the Wheatstone Bridge as discussed above.
6. Record the value of the signal conditioner's output signal and/or numeric display. This value is the shunt calibration value, or equivalent load.
7. It is important to note that the shunt calibration value is specific for the particular shunt resistor used. This value, and the particular resistor, are now matched to the transducer and form a basis of the transferable shunt calibration.

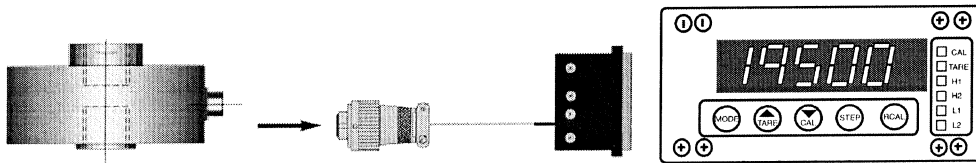
**7.0 OPERATION**

**Typical Load Cell System Configurations**

Operation requires the connection of the load cell to a signal conditioner, then to a readout device (if signal conditioner does not have a display). Strain gage signal conditioners and cable assemblies are available from PCB.

**Operation with a Signal Conditioner**

The signal conditioner span and zero must be set before the load cell system can be used. The span can be set using dead weights or the shunt calibration value. Refer to the shunt calibration information in this manual, and the signal conditioner instruction manual, for proper set-up information.



**Figure 8 - Typical Load Cell System Configuration**

**8.0 TROUBLESHOOTING**

**No output**

- ✓No power
- ✓Loose or dirty connections
- ✓Circuit opens or shorts
- ✓Faulty or improper wiring
- ✓No load applied

**Erratic or Improper Readings**

- ✓Excitation voltage drift
- ✓Electrical noise
- ✓Loose fixturing
- ✓Circuit opens or shorts
- ✓Improper load applied
- ✓Cable too long

**Blinking Display**

- ✓Overload condition
- ✓Open circuit

**Zero Balance**

- ✓Load applied to sensor
- ✓Overloaded or side-loaded sensor
- ✓Open circuit
- ✓Improper electrical connections

**Zero Shift**

- ✓Fixture preload
- ✓Faulty or improper wiring
- ✓Improper tare

**Zero Drift**

- ✓Unconditioned power supply
- ✓Circuit opens or shorts
- ✓Loose wiring
- ✓RFI/EMI interface
- ✓Temperature change

**Damaged or Deformed Equipment**

- ✓Improper use

Often overlooked by the customer, is the error due to the presence of non-measured forces and bending moments. Even Though the Single Axis of Measurement sensors are designed and built to withstand these non-measured forces and bending moments (extraneous loads), the errors due to them are present. PCB engineers can design the set-up to eliminate or minimize these extraneous loads. However, if these extraneous loads are present, the errors due to them should be considered. Due to cost restraints, the Force/Torque Division, as with its competition, does not typically measure or compensate for errors due to extraneous loads. If the presences of these extraneous loads are known, the user should request the transducer manufacturer to run a special test, at extra cost, to define and quantify the extraneous load errors. These errors are defined as cross-talk errors.

### **Error Analysis**

The Force/Torque Division typically supplies accuracy information on its products in the form of individual errors (see specification sheet). They are: Non-Linearity, Hysteresis, Non-Repeatability, Effect of Temperature on Zero, and Effect of Temperature on Output.

The customer can combine these individual errors to establish the maximum possible error for the measurement or just examine the applicable individual error. If the temperature remains stable during the test, temperature related errors may be ignored. If the sensor is used for increasing load measurement only, ignore the Hysteresis error. If the load measurement is near the full capacity, the linearity error can be ignored. If the capability exists to correct the data through linearization-fit or a look-up-table, the error in the measurement can be minimized. A sophisticated user can get rid of all the errors except for the non-repeatability error in the measurement.

## **9.0 MAINTENANCE**

Routine maintenance, such as cleaning of electrical connectors, housings, and mounting surfaces with solutions and techniques that will not harm the physical material of construction is acceptable. Caution should be observed to insure that liquids are not permitted to migrate into devices that are not hermetically sealed. Such devices should only be wiped with a damp cloth and never submerged or have liquids poured on them.

	ENGLISH	SI	
<b>Performance</b>			
Measurement Range(Full Scale Capacity)	5000 in-lb	565 N-m	
Sensitivity(output at rated capacity)	2.0 mV/V	2.0 mV/V	[4]
Non-Linearity	≤ 0.1 % FS	≤ 0.1 %	[2]
		FS	
Hysteresis	≤ 0.1 % FS	≤ 0.1 %	[2]
		FS	
Non-Repeatability	≤ 0.05 %	≤ 0.05 %	[2]
	FS	FS	
<b>Environmental</b>			
Overload Limit	10,000 in-lb	1130 N-m	
Temperature Range(Operating)	0 to 200 °F	-18 to 93 °C	
Temperature Range(Compensated)	70 to 150 °F	21 to 66 °C	
Temperature Effect on Output(Maximum)	± 0.002 % Reading/°F	± 0.0018 % Reading/°C	[3]
Temperature Effect on Zero Balance(Maximum)	± 0.002 % FS/°F	± 0.0018 %FS/°C	[3]
<b>Electrical</b>			
Bridge Resistance	350 ohm	350 ohm	
Excitation Voltage	20 VDC or VAC rms	20 VDC or VAC rms	[1]
Bridge Current(at 5 VAC)	50 mA	50 mA	
Insulation Resistance	>5 Gohm	>5 Gohm	
Zero Balance	≤ 2 % FS	≤ 2 % FS	[2]
<b>Physical</b>			
Size (Shaft Length x Housing Length x Housing Diameter x Shaft Diameter x Shaft Keyway)	11.00 in x 5.25 in x 4.50 in x 1.50 in x 3/8 in	279.4 mm x 133.4 mm x 114.3 mm x 38.1 mm x 9.5 mm	[5]
Weight	9.5 lb	4.4 kg	
Mounting	Keyed Shaft Strain Gage	Keyed Shaft Strain Gage	
Sensing Element			
Housing Material	Aluminum	Aluminum	
Shaft Material	Alloy Steel	Alloy Steel	
Electrical Connector	PT02H-10-6P	PT02H-10-6P	
Electrical Connection Position	Top	Top	
Maximum Speed	7900 RPM	7900 RPM	

**OPTIONAL VERSIONS**

Optional versions have identical specifications and accessories as listed for the standard model except where noted below. More than one option may be used.

**NOTES:**

[1] Recommended 10 VAC RMS.  
 [2] FS - Full Scale.  
 [3] Over compensated operating temperature range.  
 [4] Nominal.  
 [5] See drawing 45891 for complete dimensions.

Entered: <u>BLS</u>	Engineer: <u>PTE</u>	Sales: <u>JCC</u>	Approved: <u>MB</u>	Spec Number:
Date: <u>3-29-10</u>	Date: <u>3-29-10</u>	Date: <u>3-29-10</u>	Date: <u>3-29-10</u>	<b>45889</b>

*All specifications are at room temperature unless otherwise specified.  
 In the interest of constant product improvement, we reserve the right to change specifications without notice.*

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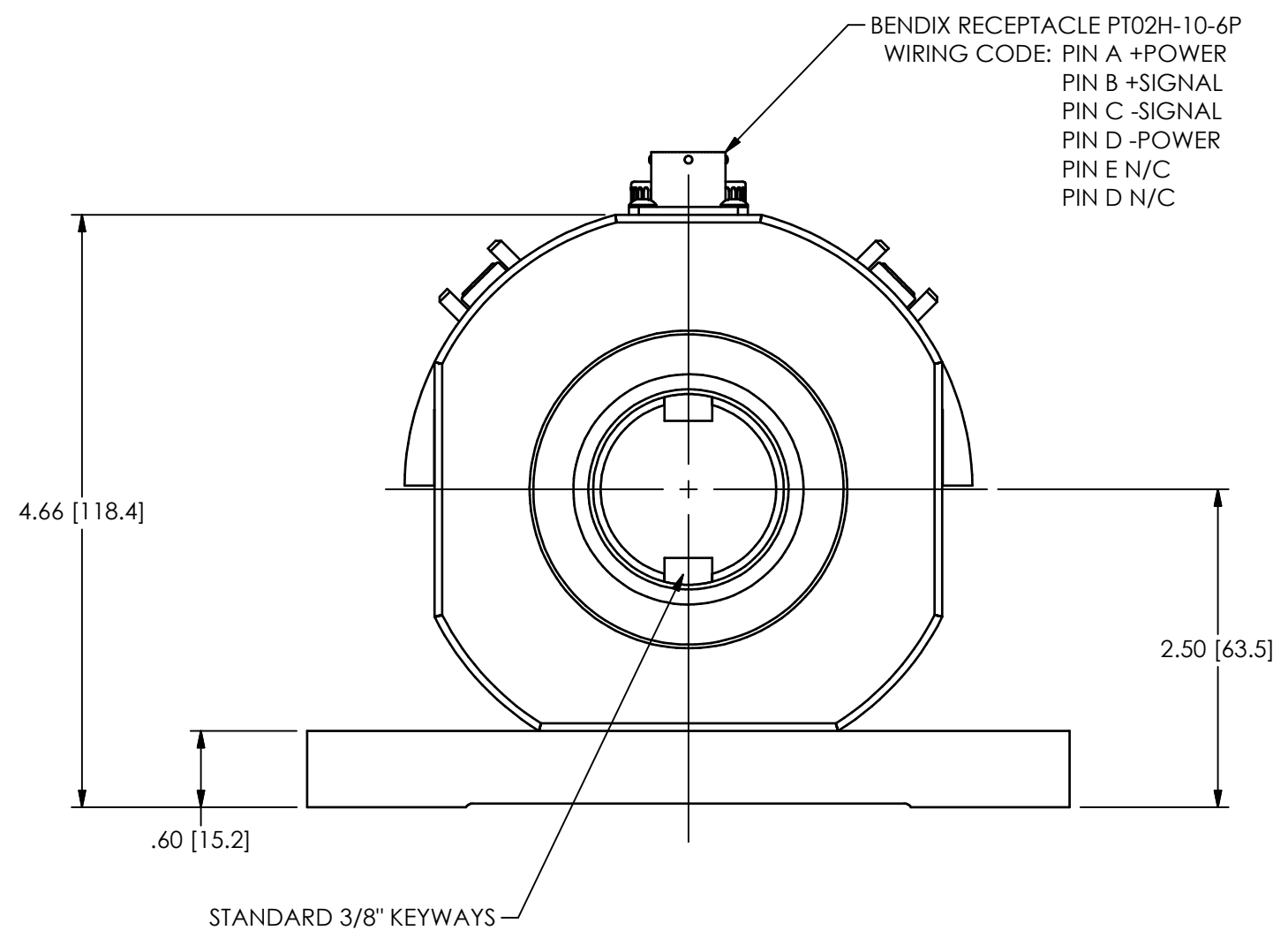
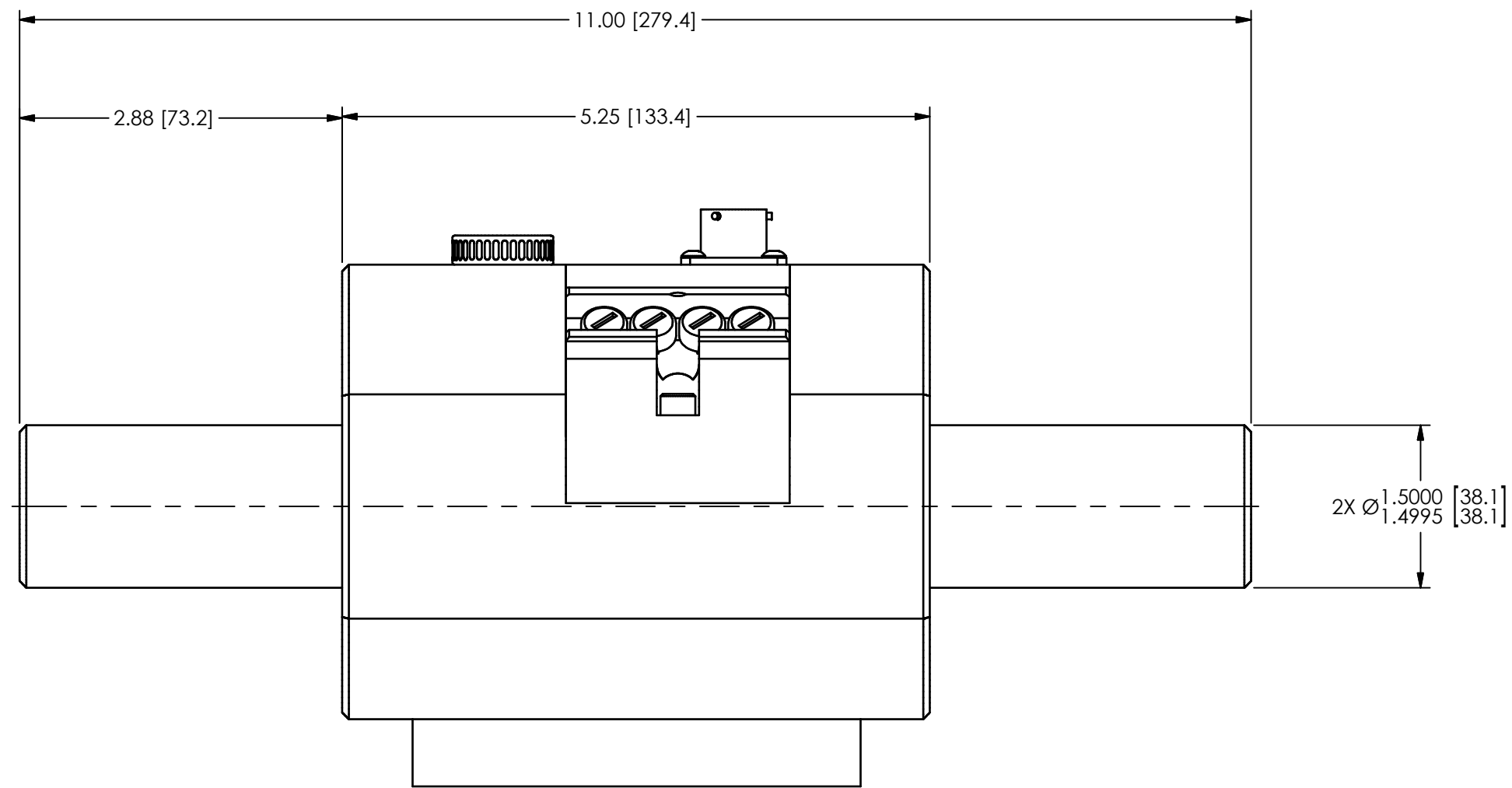
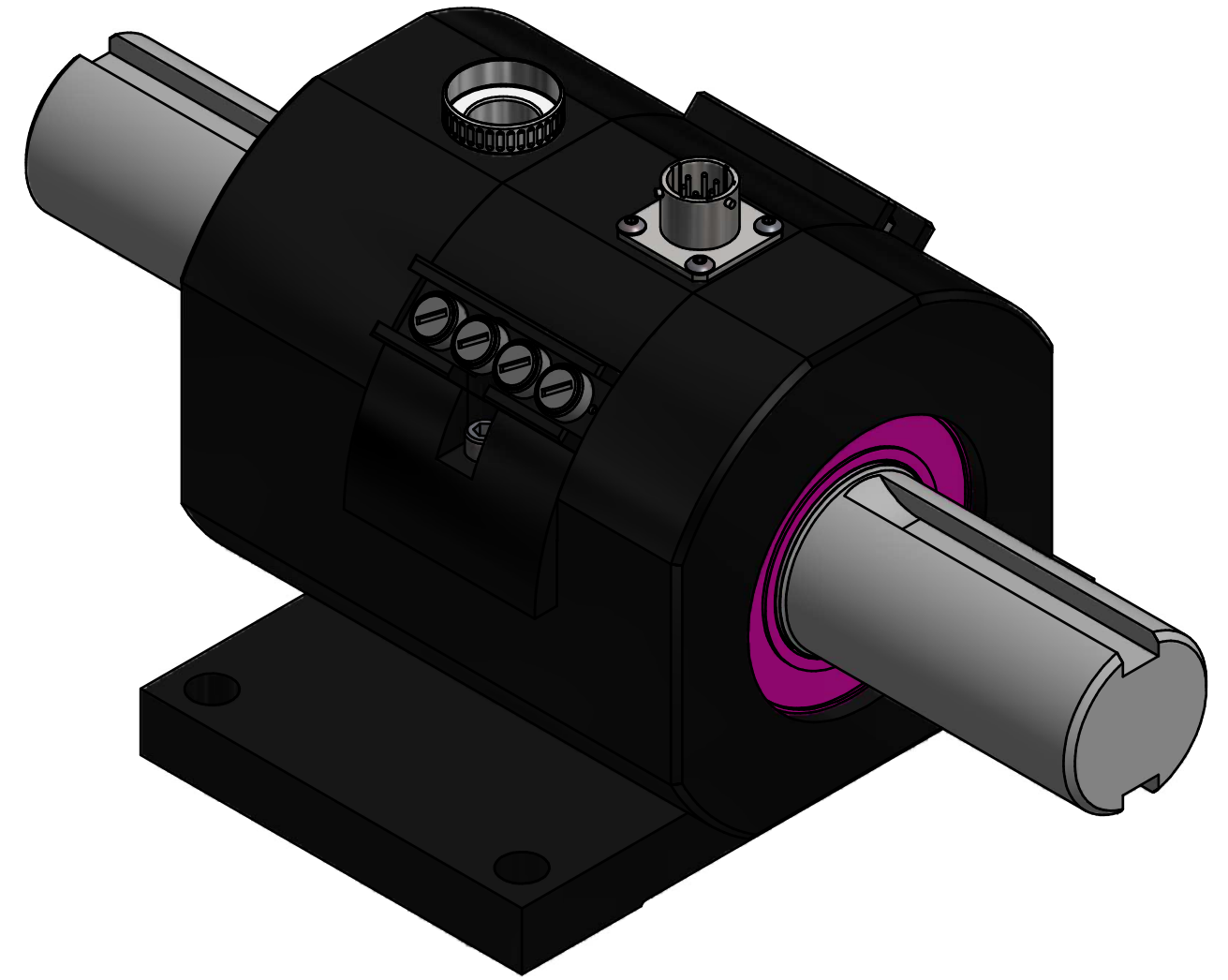
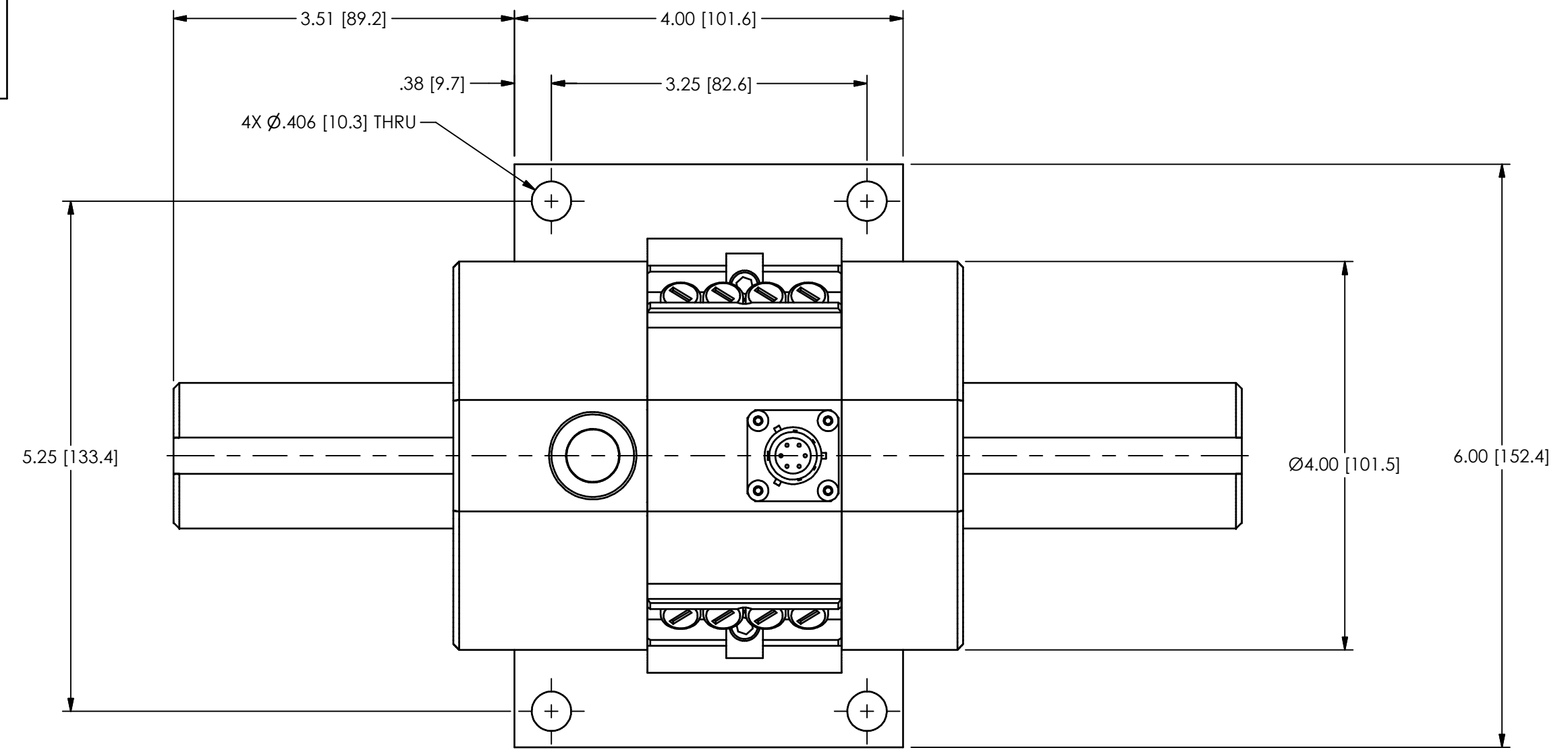
**PCB LOAD & TORQUE**  
A PCB GROUP COMPANY

**PCB Load & Torque, Inc.**  
 24350 Indoplex Circle  
 Farmington Hills, MI 48335  
 UNITED STATES  
 Phone: 866-684-7107  
 Fax: 716-684-0987  
 E-Mail: [ltinfo@pcbloadtorque.com](mailto:ltinfo@pcbloadtorque.com)  
 Web site:  
<http://www.pcbloadtorque.com>

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REVISIONS		
REV	DESCRIPTION	ECO
C	UPDATED HOLE PLUG DESIGN - 04.27.15, PTE	44064

45891



UNLESS OTHERWISE SPECIFIED TOLERANCES ARE:		DRAWN		CHECKED		ENGINEER		PCB LOAD & TORQUE A PCB GROUP COMPANY
DIMENSIONS IN INCHES	DIMENSIONS IN MILLIMETERS [IN BRACKETS]	PTE	08.10.12	PTE	08.10.12	PTE	08.10.12	
DECIMALS .XX ±0.01 XXX ±0.005	DECIMALS X ±0.3 XX ±0.13	TITLE OUTLINE DRAWING 3125 SERIES ROTARY SHAFT						24350 Indoplex Circle, Farmington Hills, MI 48335 (716) 684-0001 E-MAIL: <a href="mailto:itinfo@pcbloadtorque.com">itinfo@pcbloadtorque.com</a>
ANGLES ± .5 DEGREES	ANGLES ± .5 DEGREES							DWG. NO. <b>45891</b>
FILLET AND RADII .015 MAX	FILLET AND RADII 0.38 MAX	SCALE: 3/4						SHEET 1 OF 1